

## Homework #4

Problem 1 (a) By definition

$$\partial_i \bar{f}_\ell(x) = \lim_{\epsilon \rightarrow 0} \frac{\bar{f}_\ell(x + \epsilon \hat{e}_i) - \bar{f}_\ell(x)}{\epsilon}$$

$$= \lim_{\epsilon \rightarrow 0} \int d^3r G_\ell(r) \left[ \frac{f(x + \epsilon \hat{e}_i + r) - f(x + r)}{\epsilon} \right]$$

using the definition of  $\bar{f}_\ell$ . Under reasonable assumptions (e.g. if  $f$  is uniformly differentiable in a region of radius  $\approx \ell$  around  $x$ ), one can take the limit inside the integral to obtain

$$\partial_i \bar{f}_\ell(x) = \int d^3r G_\ell(r) \lim_{\epsilon \rightarrow 0} \left[ \frac{f(x + r + \epsilon \hat{e}_i) - f(x + r)}{\epsilon} \right]$$

$$= \int d^3r G_\ell(r) (\partial_i f)(x + r). \quad \checkmark$$

(b) Again using the definition of  $\bar{f}_\ell$ ,

$$\begin{aligned} \int d^d x \bar{f}_\ell(x) &= \int d^d x \int d^d r G_\ell(r) f(x+r) \\ &= \int d^d x \int d^d x' G_\ell(x-x') f(x') \quad w/ \quad x' \equiv x+r \end{aligned}$$

Under modest assumptions one can commute the  $x$  and  $x'$ -integrals. For example, this is possible if absolute integrability holds

$$\int d^d x \int d^d x' |G_\ell(x-x') f(x')| < \infty,$$

which will generally be true. In that case

$$\int d^d x \bar{f}_\ell(x) = \int d^d x' f(x') \left[ \int d^d x G_\ell(x-x') \right].$$

However,  $\int d^d x G_\ell(x-x') = 1$  by the normalization condition on  $G$ . Thus,

$$\int d^d x \bar{f}_\ell(x) = \int d^d x' f(x'). \quad \checkmark$$

Problem 2. We shall use

$$\begin{aligned}(f * g)(x) &= \int d^d r \, f(r) g(x-r) \\ &= \lim_{\Delta r \rightarrow 0} \sum_{i=1}^N (\Delta r)^d f(r_i) g(x-r_i)\end{aligned}$$

where  $\sum_{i=1}^N (\Delta r)^d f(r_i) g(x-r_i)$  is a finite Riemann sum which approximates the integral. Now

$$\left\| \sum_{i=1}^N (\Delta r)^d f(r_i) g(\cdot - r_i) \right\|_p \leq \sum_{i=1}^N (\Delta r)^d |f(r_i)| \cdot \|g(\cdot - r_i)\|_p$$

by the triangle inequality. Since the  $L_p$ -norm itself is shift-invariant,  $\|g(\cdot - r_i)\|_p = \|g\|_p$  for all  $i$ , and thus

$$\left\| \sum_{i=1}^N (\Delta r)^d f(r_i) g(\cdot - r_i) \right\|_p \leq \left[ \sum_{i=1}^N (\Delta r)^d |f(r_i)| \right] \cdot \|g\|_p$$

Taking the limit  $\Delta r \rightarrow 0$  and using (or assuming) that the Riemann sum converges to the integral in the  $L_p$ -norm sense,

$$\begin{aligned}\|f * g\|_p &= \left\| \lim_{\Delta r \rightarrow 0} \sum_{i=1}^N f(r_i) g(\cdot - r_i) \right\|_p \\ &\leq \lim_{\Delta r \rightarrow 0} \left\| \sum_{i=1}^N f(r_i) g(\cdot - r_i) \right\|_p\end{aligned}$$

(cont'd)

$$\leq \lim_{\Delta r \rightarrow 0} \left[ \sum_{i=1}^N (\Delta r)^d |f(r_i)| \right] \cdot \|g\|_p$$

$$= \int d^d r |f(r)| \cdot \|g\|_p = \|f\|_1 \cdot \|g\|_p$$

QED

NOTE: This is not, of course, a rigorous argument according to the standards of mathematics. For example, we assumed without any proof that

$$\| \lim R_N \|_p = \lim \| R_N \|_p$$

where  $R_N$  is the Riemann sum with  $N$ -points. Also, we should use the more general notion of the Lebesgue integral, not the Riemann integral at all. One way to derive the inequality rigorously is to derive first the special cases

$$\|f * g\|_1 \leq \|f\|_1 \cdot \|g\|_1$$

and

$$\|f * g\|_\infty \leq \|f\|_1 \cdot \|g\|_\infty$$

and then to use a general method called "Riesz-Thorin interpolation" to deduce the general case for  $1 \leq p \leq \infty$ . (In fact, the general "Young inequality for convolutions" can be obtained by a second application of Riesz-Thorin interpolation.) The above "proof" should give however an intuitive understanding of the result, as a continuous generalization of the triangle inequality,

Problem 3. (a) Note that

$$E(X_1), E(X_1 X_2), E(X_1 X_2 X_3)$$

are invariant under permutation of their arguments, by commutativity of ordinary multiplication. Furthermore,

$$C(X_1, X_2) = E(X_1 X_2) - E(X_1) \cdot E(X_2)$$

is permutation invariant, since both  $E(X_1 X_2)$  and  $E(X_1), E(X_2)$  are so.

The same argument then applies to

$$C(X_1, X_2, X_3) = E(X_1 X_2 X_3)$$

$$- \left[ E(X_1) C(X_2, X_3) + E(X_2) C(X_1, X_3) + E(X_3) C(X_1, X_2) \right]$$

$$- E(X_1) \cdot E(X_2) \cdot E(X_3),$$

since each of the three terms on the righthand side are now seen to be permutation invariant.

NOTE: This argument can be generalized to an inductive proof that all cumulants  $C(X_1, \dots, X_n)$  are permutation-invariant for every  $n$ . However, there are easier proofs!

(b) Note that

$$\begin{aligned} C(X_1 + a_1) &= E(X_1 + a_1) \\ &= \int (X_1 + a_1) dP = \int X_1 dP + a_1 \int dP = E(X_1) + a_1 \end{aligned}$$

$$\begin{aligned} C(X_1 + a_1, X_2 + a_2) &= E((X_1 + a_1)(X_2 + a_2)) - E(X_1 + a_1)E(X_2 + a_2) \\ &= E(X_1 X_2 + a_1 X_2 + a_2 X_1 + a_1 a_2) \\ &\quad - [E(X_1) + a_1][E(X_2) + a_2] \\ &= [E(X_1 X_2) + a_1 E(X_2) + a_2 E(X_1) + a_1 a_2] \\ &\quad - [E(X_1)E(X_2) + a_1 E(X_2) + a_2 E(X_1) + a_1 a_2] \\ &= E(X_1 X_2) - E(X_1)E(X_2) = C(X_1, X_2) \end{aligned}$$

For  $n=3$ , we use

$$\begin{aligned} C(X_1 + a_1, X_2 + a_2, X_3 + a_3) &= E((X_1 + a_1)(X_2 + a_2)(X_3 + a_3)) \\ &\quad - E(X_1 + a_1)C(X_2, X_3) - E(X_2 + a_2)C(X_1, X_3) - E(X_3 + a_3)C(X_1, X_2) \\ &\quad - E(X_1 + a_1)E(X_2 + a_2)E(X_3 + a_3) \quad (*) \end{aligned}$$

Then, we use

$$E((X_1 + a_1)(X_2 + a_2)(X_3 + a_3))$$

$$= E(X_1 X_2 X_3) + a_1 E(X_2 X_3) + a_2 E(X_1 X_3) + a_3 E(X_1 X_2) \\ + a_1 a_2 E(X_3) + a_1 a_3 E(X_2) + a_2 a_3 E(X_1) + a_1 a_2 a_3$$

and

$$E(X_1 + a_1) E(X_2 + a_2) E(X_3 + a_3)$$

$$= E(X_1) E(X_2) E(X_3) + a_1 E(X_1) E(X_2) + a_2 E(X_1) E(X_3) + a_3 E(X_1) E(X_2) \\ + a_1 a_2 E(X_3) + a_1 a_3 E(X_2) + a_2 a_3 E(X_1) + a_1 a_2 a_3$$

to get

$$E((X_1 + a_1)(X_2 + a_2)(X_3 + a_3)) - E(X_1 + a_1) E(X_2 + a_2) E(X_3 + a_3)$$

$$= E(X_1 X_2 X_3) - E(X_1) E(X_2) E(X_3)$$

$$+ a_1 C(X_1, X_2) + a_2 C(X_1, X_3) + a_3 C(X_1, X_2).$$

Finally, we obtain from (\*) that

$$C(X_1 + a_1, X_2 + a_2, X_3 + a_3) = E(X_1 X_2 X_3) - E(X_1) C(X_2, X_3)$$

$$- E(X_2) C(X_1, X_3) - E(X_3) C(X_1, X_2)$$

$$- E(X_1) E(X_2) E(X_3) = C(X_1, X_2, X_3).$$

QED

Problem 4, (a)

$$\begin{aligned}\tilde{f}(x) &= \int d^d r \tilde{G}(r) \bar{f}(x+r) \\ &= \int d^d r \tilde{G}(r) \left[ \int d^d r' \bar{G}(r') f(x+r+r') \right]\end{aligned}$$

Now, set

$$r'' = r + r', \quad d^d r'' = d^d r'$$

and write

$$\begin{aligned}\tilde{f}(x) &= \int d^d r \tilde{G}(r) \int d^d r'' \bar{G}(r''-r) f(x+r'') \\ &= \int d^d r'' \left[ \int d^d r \tilde{G}(r) \bar{G}(r''-r) \right] f(x+r'') \\ &\quad \underbrace{\hspace{10em}}_{(\tilde{G} * \bar{G})(r'')} \\ &= \int d^d r'' (\tilde{G} * \bar{G})(r'') f(x+r'')\end{aligned}$$

by interchanging integrals and using the definition of convolution.

Thus,

$$\tilde{G}(r'') = (\tilde{G} * \bar{G})(r'').$$

QED

$$\begin{aligned}
(b) \quad \widetilde{\tau}(f, g) &= \widetilde{fg} - \widetilde{f} \widetilde{g} \\
&= \left[ \widetilde{fg} - \widetilde{f} \widetilde{g} \right] + \left[ \widetilde{f} \widetilde{g} - \widetilde{f} \widetilde{g} \right] \\
&= \left[ \widetilde{fg} - \widetilde{f} \widetilde{g} \right] + \left[ \widetilde{f} \widetilde{g} - \widetilde{f} \widetilde{g} \right] \\
&= \widetilde{\tau}(f, g) + \widetilde{\tau}(\overline{f}, \overline{g})
\end{aligned}$$

QED

Problem 5 . By setting  $i=j$  and dividing by 2 in the evolution equation for stress, one obtains, with  $k_i = \frac{1}{2} \tau_{ii}$  (no summation on  $i$ )

$$\begin{aligned}
\partial_t k_i + \partial_k \left( \frac{1}{2} \tau_{iik} \right) &= - \overline{u_{i,k}} \tau_{ki} \\
+ \tau(p, S_{ii}) - \nu \tau(u_{i,k}, u_{i,k}) + \tau(u_i, f_i)
\end{aligned}$$

The pressure-stress term

$$\tau(p, S_{ii}) = \tau \left( p, \frac{\partial u_i}{\partial x_i} \right) \quad (\text{no summation on } i)$$

cancels when summed over  $i$

$$\sum_i \tau(p, S_{ii}) = 0.$$



Thus, there is no net gain or loss of small-scale kinetic energy  $k = \sum_i k_i$  by the pressure-strain term, which, instead, simply transfers energy between different components of the velocity. In an anisotropic flow such as a shear flow, this term is usually responsible for the transfer of energy from the "main component" — which absorbs energy directly from the mean shear — and into the "minor components." See Tenenkes & Lumley, p. 74.

Problem 6. We shall prove by induction that, for  $r < 1$ ,

$$\frac{\partial^n}{\partial r_1 \dots \partial r_n} G(r) = \exp\left(\frac{-1}{1-r^2}\right) \frac{P(r)}{(1-r^2)^{2n}}$$

where  $P(r)$  is a polynomial in the coordinates  $r_1, \dots, r_n$ . First, for  $n=1$

$$\frac{\partial}{\partial r_i} G(r) = \exp\left(\frac{-1}{1-r^2}\right) \frac{-2r_i}{(1-r^2)^2}$$

by the chain rule. This gives the result with  $P(r) = -2r_i$ .

Now assume the result for  $n$  and consider

$$\frac{\partial^{n+1}}{\partial r_1 \dots \partial r_n \partial r_{n+1}} G(r) = \frac{\partial}{\partial r_{n+1}} \left[ \exp\left(-\frac{1}{1-r^2}\right) \frac{P(r)}{(1-r^2)^{2n}} \right]$$

$$= \exp\left(\frac{-1}{1-r^2}\right) \left[ \frac{-2r_{n+1} P(r)}{(1-r^2)^{2(n+1)}} + \frac{\frac{\partial}{\partial r_{n+1}} P(r)}{(1-r^2)^{2n}} \right]$$

$$+ P(r) \frac{4nr_{n+1}}{(1-r^2)^{2n+1}} \Big]$$

$$= \exp\left(\frac{-1}{1-r^2}\right) \frac{\bar{P}(r)}{(1-r^2)^{2(n+1)}}$$

with

$$\bar{P}(r) = -2r_{n+1} P(r) + (1-r^2)^2 \frac{\partial}{\partial r_{n+1}} P(r) + 4nr_{n+1} (1-r^2) P(r)$$

a polynomial in the coordinates. This gives the stated result, by induction.

We now consider the limit from below

$$\lim_{r \rightarrow 1^-} \frac{\partial^n}{\partial r_1 \dots \partial r_n} G(r) = \lim_{r \rightarrow 1^-} \exp\left(\frac{-1}{1-r^2}\right) \frac{P(r)}{(1-r^2)^{2n}}$$

One can see that the denominators go to zero

$$(1-r^2)^{2n} \rightarrow 0$$

but the numerators go to zero even faster

$$\exp\left(\frac{-1}{1-r^2}\right) \rightarrow 0 \quad \text{faster than any polynomial}$$

This may be shown by L'Hôpital's rule (since the derivatives of  $(1-r^2)^{2n}$  becomes constant, but the derivatives of the numerator becomes  $\exp\left(\frac{-1}{1-r^2}\right)$  times a polynomial.)

Another approach is to take logarithms and to note that

$$\ln\left[\exp\left(\frac{-1}{1-r^2}\right) \frac{P(r)}{(1-r^2)^{2n}}\right]$$

$$= \frac{-1}{1-r^2} + \ln P(r) - 2n \ln(1-r^2)$$

$$\rightarrow -\infty \quad \text{as } r \rightarrow 1^-$$

Since the term  $\frac{-1}{1-r^2}$  is the largest in magnitude, from all of these arguments, we see that

$$\lim_{r \rightarrow 1^-} \frac{\partial^n}{\partial r_1 \dots \partial r_n} G(r) = 0$$

for all integers  $n$ . Thus, the definition

$$G(r) = \begin{cases} \exp\left(-\frac{1}{1-r^2}\right) & r < 1 \\ 0 & r \geq 1 \end{cases}$$

has all  $n$ th-derivatives continuous at  $r=1$ . Clearly,  $G(r)$  is  $C^\infty$  for  $r < 1$  and  $r > 1$ . Thus, we have proved that  $G(r)$  is  $C^\infty$  for all values of  $r$ .

QED

Problem 7. (a) Observing as in the classnotes that

$$\begin{aligned} 2\nu(\nabla \cdot \mathbf{S})_i &= \nu \partial_j (\partial_i u_j + \partial_j u_i) \\ &= \nu (0 + \partial_j^2 u_i) = \nu (\Delta \mathbf{v})_i \end{aligned}$$

we see that the two forms of the momentum equation

$$\partial_t \mathbf{v} + (\mathbf{v} \cdot \nabla) \mathbf{v} = -\nabla p + \nu \Delta \mathbf{v}$$

and

$$\partial_t \mathbf{v} + \nabla \cdot (\mathbf{v}\mathbf{v} + p\mathbf{I} - 2\nu\mathbf{S}) = 0$$

are equivalent for smooth solutions with the condition  $\nabla \cdot \mathbf{v} = 0$ .

These two equations thus also imply the kinetic energy balance equation as discussed in the classnotes

$$\begin{aligned} (1) \quad \partial_t \left( \frac{1}{2} |\mathbf{v}|^2 \right) + \nabla \cdot \left[ \left( \frac{1}{2} |\mathbf{v}|^2 + p \right) \mathbf{v} - 2\nu \mathbf{S} \cdot \mathbf{v} \right] &= -2\nu |\mathbf{S}|^2 \\ &= -\varepsilon. \end{aligned}$$

Writing the Fourier temperature equation in the form

$$(2) \quad \partial_t (c_p T) + \nabla \cdot (c_p T \mathbf{v} - (k/\rho) \nabla T) = \varepsilon,$$

we see that the sum of the last two equations gives

$$(3) \quad \partial_t \left( \frac{1}{2} |\mathbf{v}|^2 + c_p T \right) + \nabla \cdot \left[ \left( \frac{1}{2} |\mathbf{v}|^2 + c_p T + p \right) \mathbf{v} - 2\nu \mathbf{S} \cdot \mathbf{v} - (k/\rho) \nabla T \right] = 0$$

in conservation form.

On the other hand, the conservation equation (3) for total energy per mass  $\frac{1}{2}|\mathbf{v}|^2 + c_p T$  minus the equation (1) for kinetic energy per mass gives the equation (2) which is equivalent to the temperature equation

$$\partial_t T + (\mathbf{v} \cdot \nabla) T = \lambda_T \Delta T + \varepsilon / c_p.$$

Thus, the two systems of equations are entirely equivalent.

(b) We can evaluate the term involving  $\kappa$  as

$$\nabla \cdot \left[ \overline{\left( \frac{\kappa}{\rho} \nabla T \right)_\ell} \right] = -\frac{1}{\ell \rho} \int d^d r (\nabla G)_\ell(\mathbf{r}) \kappa(\mathbf{x}+\mathbf{r}) \nabla T(\mathbf{x}+\mathbf{r}).$$

$$= -\frac{1}{\ell \rho} \int d^d r \mathbb{1}_{\text{supp} G_\ell}(\mathbf{r}) \sqrt{\kappa(\mathbf{x}+\mathbf{r})}$$

$$(\nabla G)_\ell(\mathbf{r}) \times \sqrt{\kappa(\mathbf{x}+\mathbf{r})} \nabla T(\mathbf{x}+\mathbf{r})$$

so that applying Cauchy-Schwarz inequality gives

$$\left| \nabla \cdot \left[ \overline{\left( \frac{\kappa}{\rho} \nabla T \right)_\ell} \right] \right| \leq \frac{1}{\ell \rho} \sqrt{\int_{\text{supp} G_\ell} d^d r \kappa(\mathbf{x}+\mathbf{r})} \\ \times \sqrt{\int d^3 r |(\nabla G)_\ell(\mathbf{r})|^2 \kappa(\mathbf{x}+\mathbf{r}) |\nabla T(\mathbf{x}+\mathbf{r})|^2}$$

If we assume that, for fixed  $l$ ,

$$\int_{\text{supp} G_l} d^d r \kappa(\mathbf{x}+\mathbf{r}) \rightarrow 0$$

with

$$\int d^3 x \varphi(\mathbf{x}) \kappa(\mathbf{x}) |\nabla T(\mathbf{x})|^2$$

remaining finite for compactly-supported,  $C^\infty$  functions  $\varphi$ , then we see that, for fixed  $l$ ,

$$|\nabla \cdot [(\kappa/l) \nabla T]_l(\mathbf{x})| \rightarrow 0.$$

In a similar fashion, the term

$$\nabla \cdot [2(\mathbf{v} \cdot \mathbf{S} \cdot \mathbf{v})_l] = -\frac{1}{l} \int d^d r (\nabla G)_l(\mathbf{r}) \cdot \mathbf{v}(\mathbf{x}+\mathbf{r}) \cdot \mathbf{S}(\mathbf{x}+\mathbf{r}) \mathbf{v}(\mathbf{x}+\mathbf{r})$$

$$= -\frac{1}{l} \int d^d r \mathbb{1}_{\text{supp} G_l}(\mathbf{r}) \sqrt{v(\mathbf{x}+\mathbf{r})} v_i(\mathbf{x}+\mathbf{r})$$

$$\times \sqrt{v(\mathbf{x}+\mathbf{r})} S_{ij}(\mathbf{x}+\mathbf{r}) (\partial_j G)_l(\mathbf{r}).$$

Applying Cauchy-Schwarz again with the above factorization of the integrand yields

$$|\nabla \cdot [2(\nu \mathbf{S} \cdot \nu)_\ell(\mathbf{x})]| \leq \frac{1}{\ell} \sqrt{\int_{\text{supp} G_\ell}^d d\mathbf{r} \nu(\mathbf{x}+\mathbf{r}) |\mathbf{v}(\mathbf{x}+\mathbf{r})|^2} \\ \times \sqrt{\int_{\text{supp} G_\ell}^d d\mathbf{r} |(\nabla G)_\ell(\mathbf{r})|^2 \nu(\mathbf{x}+\mathbf{r}) |\mathbf{S}(\mathbf{x}+\mathbf{r})|^2}$$

Thus, assuming that

$$(*) \quad \int_{\text{supp} G_\ell}^d d\mathbf{r} \nu(\mathbf{x}+\mathbf{r}) |\mathbf{v}(\mathbf{x}+\mathbf{r})|^2 \rightarrow 0$$

and that  $\int_{\text{supp} G_\ell}^d d\mathbf{x} \varphi(\mathbf{x}) \nu(\mathbf{x}) |\mathbf{S}(\mathbf{x})|^2$  remains finite for smooth, compactly supported test functions, we see that

$$|\nabla \cdot [2(\nu \mathbf{S} \cdot \nu)_\ell(\mathbf{x})]| \rightarrow 0.$$

Note that (\*) follows because

$$\int_{\text{supp} G_\ell}^d d\mathbf{r} \nu(\mathbf{x}+\mathbf{r}) |\mathbf{v}(\mathbf{x}+\mathbf{r})|^2 \\ \leq \left[ \sup_{\mathbf{r} \in \text{supp} G_\ell} \nu(\mathbf{x}+\mathbf{r}) \right] \int_{\text{supp} G_\ell}^d d\mathbf{r} |\mathbf{v}(\mathbf{x}+\mathbf{r})|^2$$

with total kinetic energy  $\int_{\text{supp} G_\ell}^d d\mathbf{r} |\mathbf{v}(\mathbf{x}+\mathbf{r})|^2$  finite and  $\sup_{\mathbf{r} \in \text{supp} G_\ell} \nu(\mathbf{x}+\mathbf{r}) \rightarrow 0$ ,