Problam 1, (0) We calculate that $\int (\nabla \cdot \mathbf{F}) \varphi \, dV := - \int \mathbf{F} \cdot \nabla \varphi \, dV$ \mathbb{R}^{3} = - SF. VQ dV - SF. VQ dV R. $= \int \left[(\nabla \cdot F_1) \varphi - \nabla \cdot (F_1 \varphi) \right] dV + \int \left[(\nabla \cdot F_2) \varphi - \nabla \cdot (F_2 \varphi) \right] dV$ $= \int \{\nabla \cdot \mathbf{F}\} \langle \mathbf{p} \, dV - \int (\nabla \cdot \mathbf{F}_1) \langle \mathbf{p} \, dA + \int (\nabla \cdot \mathbf{F}_2) \langle \mathbf{p} \, dA \\ \partial \mathcal{R}_1, \qquad \partial \mathcal{R}_2, \qquad \partial \mathcal{R}_2, \qquad \partial \mathcal{R}_2$ by the diversance therein $= \int \{\nabla \cdot F_{3}^{2} \varphi^{AV} + \int n \cdot [F] dA$ $R^{3} \qquad \partial \mathcal{I}$ using [F]= F2 -F $= \int_{\mathbb{R}^{3}} \left(\{ \nabla \cdot F \} + n \cdot [F] \delta(d) \right) dV$ since $\partial \Omega = \{x \in \mathbb{R}^3 : d(x) = 0\}$ and d(d)dV = dA a dR $\nabla \cdot \mathbf{F} = \{ \nabla \cdot \mathbf{F} \} + \mathbf{n} \cdot [\mathbf{F}] \delta(d) .$ Thus,

(b) Likewise, we calculate

and thus

$$\nabla \times F = \{\nabla \times F\} + n \times [F] \delta(d)$$
.

Publem 2. (a) Using the definition of vorticity

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$$\int_{\Omega} x_i' \omega_j' dV' = \int_{\Omega} x_i' \epsilon_{jke} \partial_k' u_k' dV'$$

$$= -\int_{\Omega} \overline{\delta_{ik}} \epsilon_{jke} u_k' dV'$$

$$-\int_{\Omega} x_i' \epsilon_{jke} n_k' u_k' dA' \qquad by interretion by parts$$

$$= \int_{\Omega} \epsilon_{ijk} u_k' dV' - \int_{\Omega} x_i' (n \times u')_j dA'$$

$$= \int_{\Omega} x_i' \omega_j' dV' + \int_{\partial B} x_i' (n \times u')_j dA' = \int_{\Omega} \epsilon_{ijk} u_k' dV'$$

$$= \int_{\Omega} x_i' \omega_j' dV' + \int_{\partial B} x_i' (n \times u')_j dA' = \int_{\Omega} \epsilon_{ijk} u_k' dV'$$

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$$= \int_{\Omega} x_i' \omega_j' dV' + \int_{\partial B} x_i' (n \times u')_j dA' = \int_{\Omega} x_i' (n \times u')_j dA' = \int_{$$

$$\mathbf{I} \times \mathbf{x} = \frac{1}{2} \int_{\Omega} (\mathbf{x}' \times \mathbf{w}') \times \mathbf{x} \, dV' + \frac{1}{2} \int (\mathbf{x}' \times (\mathbf{n} \times \mathbf{u}')) \times \mathbf{x} \, dA$$

$$= \frac{1}{2} \mathbf{x}^{T} \cdot \mathbf{J} - \frac{1}{2} \mathbf{J} \cdot \mathbf{x}$$

$$= \mathbf{x}^{T} \cdot \mathbf{J} \quad \text{sunce} \quad \mathbf{J} = -\mathbf{J}^{T}$$

$$= \int (\mathbf{x} \cdot \mathbf{x}') \mathbf{w}' \, dV' + \int (\mathbf{x} \cdot \mathbf{x}) (\mathbf{n} \times \mathbf{u}') \, dA,$$

$$= \int_{\Omega} (\mathbf{x} \cdot \mathbf{x}') \mathbf{w}' \, dV' + \int_{\Omega} (\mathbf{x} \cdot \mathbf{x}) (\mathbf{n} \times \mathbf{u}') \, dA,$$

Problem 3. (a) Using the definition of variatity,

$$(\mathbf{x} \mathbf{x} \mathbf{w})_{i} = \mathcal{E}_{ijk} \mathbf{x}_{j} \mathbf{w}_{k}$$
$$= \mathcal{E}_{ijk} \mathcal{E}_{kem} \mathbf{x}_{j} \partial_{e} \mathbf{u}_{m}$$
$$= (\delta_{ie} \delta_{jm} - \delta_{im} \delta_{je}) \mathbf{x}_{j} \partial_{e} \mathbf{u}_{m}$$
$$= \mathbf{x}_{j} \partial_{i} \mathbf{u}_{j} - (\mathbf{x} \cdot \nabla) \mathbf{u}_{i}$$

or $\mathbf{x} \mathbf{x} \mathbf{w} = \mathbf{x}_j \nabla \mathbf{u}_j - \langle \mathbf{x}_j \nabla \mathbf{u} \rangle_{\mathbf{u}_j}$

$$\int \mathbf{x} \times \mathbf{w} \, dV = \int (\mathbf{x}_j \cdot \nabla \mathbf{u}_j - (\mathbf{x} \cdot \nabla \mathbf{u}_j) \, dV$$

+
$$\lim_{R \to \infty} \int \left[(\mathbf{x} \cdot \mathbf{u}) \cdot \mathbf{x} - (\mathbf{x} \cdot \cdot \mathbf{x}) \mathbf{u} \right] dA$$

R- $\sum_{R \to \infty} \int_{R} \left[(\mathbf{x} \cdot \mathbf{u}) \cdot \mathbf{x} - (\mathbf{x} \cdot \mathbf{x}) \mathbf{u} \right] dA$

$$2I = \int x * w \, dV + \int x * (n * u) \, dA$$

= 2 $\int u \, dV + \lim_{R \to \infty} \int x * (\hat{x} * u) \, dA$
 $x = 2 \int u \, dV + \lim_{R \to \infty} \int x * (\hat{x} * u) \, dA$

(c) From the leading term in the asymptotic multipole expansion

$$\mathbf{u}(\mathbf{x}) \sim -\frac{\mathbf{I}}{4\pi r^{3}} + \frac{3(\mathbf{I} \cdot \mathbf{x})\mathbf{x}}{4\pi r^{3}} + O\left(\frac{1}{r^{4}}\right)$$

one can see that

$$\vec{x} \times u \sim \frac{\mathbf{I} \times \vec{x}}{4\pi r^3} + O(\frac{1}{r^4})$$

and thus

$$x \times (\hat{x} \times u) \sim \frac{\hat{x} \times (\mathbf{I} \times \hat{x})}{4\pi r^2} + O\left(\frac{1}{r^3}\right)$$

$$= \frac{\mathbf{I} - (\mathbf{I} \cdot \hat{x})\hat{x}}{4\pi r^2} + O\left(\frac{1}{r^3}\right)$$

$$\Longrightarrow \lim_{R \to \infty} \int x \times (\hat{x} \times u) dA = \lim_{R \to \infty} \int \frac{\mathbf{I} - (\mathbf{I} \cdot \hat{x})\hat{x}}{4\pi r^2} R^2 d\mathcal{D} = \frac{2}{3}\mathbf{I}$$

$$using \frac{1}{4\pi} \int \hat{x}_i \hat{x}_j d\mathcal{D} = \frac{1}{3}\delta_{ij}. \text{ From } 2\mathbf{I} = 2\mathbf{P} + \frac{2}{3}\mathbf{I}, \text{ are easily gets}$$

$$\mathbf{P} = \frac{z}{3}\mathbf{I}$$

Problem 4 (a) We observe that

$$\begin{split} \sum_{\mathbf{z}} \mathbf{u}_{\phi} \cdot \mathbf{u} \times \mathbf{w} \, dV &= \int_{\Omega} \mathbf{u}_{\phi} \cdot \mathbf{u}_{\phi} \times \mathbf{w} \, dV \\ &= \int_{\Omega} \mathbf{u}_{\phi} \cdot \left[-\nabla \cdot (\mathbf{u}_{\omega} \mathbf{u}_{\omega}) + \nabla \left(\frac{1}{2} |\mathbf{u}_{\omega}|^{2} \right) \right] dV \\ &= \lim_{\Delta \mathbf{u}} \int_{\Omega} \mathbf{u}_{\phi} \cdot \left[-\nabla \cdot (\mathbf{u}_{\omega} \mathbf{u}_{\omega}) + \nabla \left(\frac{1}{2} |\mathbf{u}_{\omega}|^{2} \right) \right] dV \\ &= \lim_{R \to \infty} \int_{\Omega_{R}} \Omega_{R} = \mathcal{D} \prod \mathcal{B}_{R}^{(0)} \\ &= \int_{\Omega} \left[\nabla \mathbf{u}_{\phi} : \mathbf{u}_{\omega} \mathbf{u}_{\omega} - \left(\nabla \cdot \mathbf{u}_{\phi}^{2} \right) \frac{1}{2} |\mathbf{u}_{\omega}|^{2} \right] dV \\ &+ \int_{\Omega_{R}} \left[(\pi \cdot \mathbf{u}_{\omega}) (\mathbf{u}_{\omega} \cdot \mathbf{u}_{\phi}) - (\pi \cdot \mathbf{u}_{\phi}^{2}) \frac{1}{2} |\mathbf{u}_{\omega}|^{2} \right] dA \\ &- \lim_{\Omega_{R}} \int_{\Omega_{R}} \left[(\hat{\mathbf{x}} \cdot \mathbf{u}_{\omega}) (\mathbf{u}_{\omega} \cdot \mathbf{u}_{\phi}) - (\hat{\mathbf{x}} \cdot \mathbf{u}_{\phi}) \frac{1}{2} |\mathbf{u}_{\omega}|^{2} \right] dA. \end{split}$$

Note that the last limit vanishes, since

$$u_{q} \sim V$$
, $u_{\omega} = O\left(\frac{1}{r^{3}}\right)$, $r \rightarrow \infty$

and thus

$$\int \mathbf{u}_{\mathbf{q}} \cdot \mathbf{u} \times \mathbf{w} \, dV = \int \nabla \mathbf{u}_{\mathbf{q}} \cdot \mathbf{u}_{\mathbf{w}} \mathbf{u}_{\mathbf{w}} \, dV,$$

 $\mathbf{v} \quad \mathbf{v}$

$$\nabla \cdot (\mathbf{w} \times \mathbf{u}_{\phi}) = \mathbf{u}_{\phi} \cdot \nabla \times \mathbf{w} - \mathbf{w} \cdot \nabla \times \mathbf{u}_{\phi}$$

and thus

$$\begin{aligned}
\int u_{\varphi} \cdot v \nabla x \cdot w \, dV &= v \int \nabla \cdot (w \times u_{\varphi}) \, dV \\
&= \lim_{R \to \infty} v \int \nabla \cdot (w \times u_{\varphi}) \, dV \\
&= -v \int n \cdot (w \times u_{\varphi}) \, dA \\
&= \partial B \\
&+ \lim_{R \to \infty} v \int x \cdot (w \times u_{\varphi}) \, dA. \\
&= R \to \infty S_R
\end{aligned}$$

The last limit vanishes gain because $u_q \sim V$, $w = O(\frac{1}{r^4})$ as $r \rightarrow \infty$. We conclude that

$$\int u_{\phi} \cdot v \nabla \times w \, dV = \int u_{\phi} \cdot (v w \times n) \, dA$$

Since Tw = VW×n.

Problem 5. (a) Note from the definition

$$u(x,t) = \overline{u}(x + X(t),t) - V(t)$$

and the chain me that

$$\partial_{t} \mathbf{u} = \partial_{t} \overline{\mathbf{u}} + (\mathbf{V}(t) \cdot \overline{\mathbf{v}}) \overline{\mathbf{u}} - \mathbf{A}(t)$$

$$= \left(-(\overline{\mathbf{u}} \cdot \overline{\mathbf{v}}) \overline{\mathbf{u}} - \overline{\mathbf{v}} \overline{p} + v \overline{\Delta} \overline{\mathbf{u}} \right)$$

$$+ \left(\mathbf{V}(t) \cdot \overline{\mathbf{v}} \right) \overline{\mathbf{u}} - \mathbf{A}(t)$$

$$= -\left((\overline{\mathbf{u}} \cdot \mathbf{v}) \cdot \overline{\mathbf{v}} \overline{\mathbf{u}} - \overline{\mathbf{v}} (\overline{\mathbf{u}} + \mathbf{A}(t) \cdot \mathbf{v}) + \mathbf{v} \right)$$

$$= -((\overline{\mathbf{u}} - \mathbf{V}) \cdot \overline{\mathbf{v}} - \overline{\mathbf{v}} - \overline{\mathbf{v}} + \mathbf{A} + \mathbf{v} \overline{\mathbf{v}} + \mathbf{v} \overline{\mathbf{v}}$$

$$= -(\mathbf{u} \cdot \nabla)\mathbf{u} - \nabla \mathbf{p} + \mathbf{v} \Delta \mathbf{u}$$

using in the last step the definition

$$p(\mathbf{x}, t) = \overline{P}(\mathbf{x} + \mathbf{X}(t), t) + \mathbf{A}(t) \cdot \mathbf{x}.$$

Furthermore,

$$|a| = |a| - V(t) = V(t) - V(t) = 0$$

and

$$\lim_{|x| \to \infty} u = \lim_{|x| \to \infty} \overline{u} - V = o - V = -V$$

(b) Note from the definition

$$\phi(\mathbf{x},+) = \overline{\phi}(\mathbf{x}+\mathbf{X}(+),+) - \mathbf{V}(+).\mathbf{x}$$

and the chain me that

$$\partial_{+}\phi = \partial_{+}\overline{\phi} + (V(+).\overline{\nabla})\overline{\phi} - A(+).\times$$
$$= \left(-\frac{1}{2}|\overline{\nabla}\overline{\phi}|^{2} - \overline{P}\phi + \overline{C}(+)\right)$$
$$+ (V(+).\overline{\nabla})\overline{\phi} - A(+).\times.$$

Since
$$\nabla \phi = \overline{\nabla} \phi - V(t)$$
,

$$\frac{1}{2} |\nabla \phi|^2 = \frac{1}{2} (\overline{\nabla} \overline{\phi}|^2 - V(t) \cdot \overline{\nabla} \phi + \frac{1}{2} |V(t)|^2$$
and thus we obtain the Bernoulli equation for ϕ

$$\partial_{t} \phi = \left(-\frac{1}{2} |\nabla \phi|^{2} + \frac{1}{2} |\nabla (t)|^{2} \right) - \left(\overline{p}_{\phi} + A(t) \cdot x \right) + \overline{c}(t)$$

$$= -\frac{1}{2}|\nabla q|^2 - P_q + c(t)$$

with $P_{\phi}(\mathbf{x},t) = \overline{P_{\phi}}(\mathbf{x} + \mathbf{X}(t), t) + \mathbf{A}(t) \cdot \mathbf{x}$ and $C(t) = \overline{C}(t) + \frac{1}{2}[\mathbf{V}(t)]^{2}$. Finally,

$$\frac{\partial \Phi}{\partial n} = \frac{\partial \Phi}{\partial n} = V(H) \cdot n = V(H) \cdot n = 0$$

and

$$\varphi = \overline{\varphi} - V(t) \cdot x \sim \varphi - V(t) \cdot x = -V(t) \cdot x$$

as $|X| \rightarrow \infty$, and, of course, $\Delta \phi = \overline{\Delta} \overline{\phi} = 0$.

$$\frac{Pnblem6}{S} (o) Note that
$$\int u_{\varphi} dV = \lim_{R \to \infty} \int \nabla \varphi \, dV$$

$$R \to \infty R$$

$$= -\int m \varphi \, dA + \lim_{R \to \infty} \int \hat{x} \varphi \, dA$$

$$R \to \infty S_{R}$$$$

but the latter limit diverges, because $\phi \sim -V(t) \cdot x$ as $|x| \rightarrow \infty$. Defining $P_{\phi} = -\int \phi \mathbf{n} \, dA$, we obtain from the Bernaulli velation ∂B

$$\frac{dP_{\phi}}{dt} = -\int_{B}^{2} \phi \, \mathbf{n} \, dA$$

$$= \int \left(P_{\phi} + \frac{1}{2} |\mathbf{u}_{\phi}|^{2} - c(t_{1}) \right) \mathbf{n} \, dA$$

$$= \partial B$$

(b) Note First that

$$\nabla u_{\phi} = \nabla \nabla \phi$$

is symmetric and thus

$$\partial_i \left(\frac{1}{2} |\mathbf{u}_{\phi}|^2 \right) = \mathbf{u}_{\phi} \cdot \partial_i \mathbf{u}_{\phi} = \mathbf{u}_{\phi} \cdot \nabla_{u_{\phi}}$$

 $\nabla\left(\frac{1}{2}|\mathbf{u}_{\phi}|^{2}\right) = (\mathbf{u}_{\phi} \cdot \nabla)\mathbf{u}_{\phi}$

Thus,

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$$\int \nabla \left(\frac{1}{2} \left[u_{\phi} \right]^{2} \right) dV = \int \left(u_{\phi} \cdot \nabla \right) u_{\phi} dV$$

$$\Re R$$

$$\Re R$$

implying that

$$-\int r \frac{1}{2} |u_{\varphi}|^{2} dA + \int x \frac{1}{2} |u_{\varphi}|^{2} dA$$

$$= -\int (u_{\varphi}, \vec{n}) u_{\varphi} dA + \int (u_{\varphi}, \vec{x}) u_{\varphi} dA.$$
From the proof of the d'Alembert theorem, we know that

$$u_{\varphi} = -V(t_{1} + \widetilde{u}_{\varphi}, \quad \widetilde{u}_{\varphi} = O(\frac{1}{r^{3}}) \text{ es } r \rightarrow \infty,$$
Since $\int x dA = 0$, we obtain
 S_{R}

$$\lim_{R \to \infty} \int x \frac{1}{2} |u_{\varphi}|^{2} dA = \lim_{R \to \infty} -\int x (V(t_{1}) \cdot \widetilde{u}_{\varphi}) dA = 0$$

$$\frac{\lim_{R \to \infty} S_{R}}{R}$$

$$\lim_{R \to \infty} \int (u_{\phi} \cdot \hat{x}) u_{\phi} dA = \lim_{R \to \infty} - \int [(V(H) \cdot \hat{x}) \tilde{u}_{\phi} + (\tilde{u}_{\phi} \cdot \hat{x}) V(H)] dA$$

$$R \to \infty \quad S_{R}$$

$$= 0$$

and we thus conclude that

$$\int \frac{1}{2} |u\varphi|^2 n \, dA = 0 \, .$$

(c) From parts (a) and (b) we thus obtain that

$$\frac{dP_{q}(t)}{dt} = \int P_{q} n dA = F_{q}.$$

Recalling that & satisfies

$$-\Delta \phi = 0 \quad \text{in } \mathcal{D}$$

$$\frac{\partial \phi}{\partial n} = -V(4) \cdot n \quad m \quad \partial B$$

$$\phi \rightarrow 0 \quad \text{as } |\mathbf{x}| \rightarrow \infty,$$

then it follows from the theory of the Neumann public for the Loplace equation that & will be bounded whenever V(t) is bounded. In that case,

$$\begin{split} \overline{F}_{\phi} &= \lim_{T \to \infty} \frac{1}{T} \int_{0}^{T} \overline{F}_{\phi}(t) dt \\ &= \lim_{T \to \infty} \frac{1}{T} \int_{0}^{T} \frac{dP_{\phi}}{dt}(t) dt \\ &= \lim_{T \to \infty} \frac{1}{T} \int_{0}^{T} \frac{P_{\phi}(T)}{dt} - P_{\phi}(0) \end{bmatrix} = 0, \end{split}$$

so that the long-time average of the force vanishes,