

## Homework #1

Problem 1, a) Starting from Fourier's equation in the form

$$\partial_t T + \nabla \cdot (\mathbf{v}T - \kappa \nabla T) = \varepsilon / c_p$$

we obtain by coarse-graining

$$\partial_t \overline{T}_\ell + \nabla \cdot \left[ \overline{(\mathbf{v}T)}_\ell - \overline{(\kappa \nabla T)}_\ell \right] = \overline{\varepsilon}_\ell / c_p.$$

By the result of Homework #1, Problem 1(b)

$$\lim_{\nu, \kappa \rightarrow 0} \nabla \cdot \overline{(\kappa \nabla T)}_\ell = 0$$

so that we obtain, using also  $\overline{(\mathbf{v}T)}_\ell = \overline{\mathbf{v}}_\ell \overline{T}_\ell + \tau_\ell(\mathbf{v}, T)$ ,

$$\partial_t \overline{T}_\ell + \nabla \cdot \left[ \overline{\mathbf{v}}_\ell \overline{T}_\ell + \tau_\ell(\mathbf{v}, T) \right] = \overline{\varepsilon}_\ell / c_p$$

in the limit  $\nu, \kappa \rightarrow 0$ . This can be also written as

$$(\partial_t + \overline{\mathbf{v}}_\ell \cdot \nabla) \overline{T}_\ell + \nabla \cdot \tau_\ell(\mathbf{v}, T) = \overline{\varepsilon}_\ell / c_p$$

using the incompressibility condition  $\nabla \cdot \overline{\mathbf{v}}_\ell = 0$ . Then, dividing this last equation by  $\overline{T}_\ell$  and multiplying by  $\rho c_p$  gives

$$(\partial_t + \bar{\mathbf{v}}_l \cdot \nabla) \underbrace{(\rho c_p \ln \bar{T}_l)}_{\underline{s}_l} + \underbrace{\frac{\rho c_p}{\bar{T}_l} \nabla \cdot \mathbf{T}_l(T, \mathbf{v})}_{\frac{1}{\bar{T}_l} \nabla \cdot \mathbf{T}_l(u, \mathbf{v})} = \rho \bar{\varepsilon}_l / \bar{T}_l$$

Then, by writing

$$\frac{1}{\bar{T}_l} \nabla \cdot \mathbf{T}_l(u, \mathbf{v}) = \nabla \cdot \left[ \frac{1}{\bar{T}_l} \mathbf{T}_l(u, \mathbf{v}) \right] - \nabla \left( \frac{1}{\bar{T}_l} \right) \cdot \mathbf{T}_l(u, \mathbf{v})$$

and again using incompressibility, we get

$$\partial_t \underline{s}_l + \nabla \cdot \left[ \underline{s}_l \bar{\mathbf{v}}_l + \underline{\beta}_l \mathbf{T}_l(u, \mathbf{v}) \right] = \nabla \underline{\beta}_l \cdot \mathbf{T}_l(u, \mathbf{v}) + \underline{\beta}_l \rho \bar{\varepsilon}_l$$

for  $\underline{\beta}_l := 1/\bar{T}_l$ , as stated.

(b) Taking  $\bar{D}_t = \partial_t + \bar{\mathbf{v}}_l \cdot \nabla$ , the product rule gives

$$\bar{D}_t (\underline{\beta}_l \rho k_l) = (\bar{D}_t \underline{\beta}_l) \rho k_l + \underline{\beta}_l (\bar{D}_t \rho k_l).$$

The balance equation for  $\rho k_l$  can be rewritten as

$$\begin{aligned} \bar{D}_t (\rho k_l) + \nabla \cdot \left[ \mathbf{T}_l(P, \mathbf{v}) + \frac{1}{2} \rho \underline{\sigma}_l(v_i, v_i, \mathbf{v}) \right] \\ = \rho \Pi_l - \rho \bar{\varepsilon}_l \end{aligned}$$

so that

$$\bar{D}_t(\underline{\beta}_\ell e k_\ell) = (\bar{D}_t \underline{\beta}_\ell) e k_\ell + e \underline{\beta}_\ell \pi_\ell - e \underline{\beta}_\ell \bar{\varepsilon}_\ell - \underline{\beta}_\ell \nabla \cdot \left[ \tau_\ell(P, \mathbf{v}) + \frac{1}{2} e \tau_\ell(v_i, v_i, \mathbf{v}) \right].$$

Rewriting the last term as

$$\underline{\beta}_\ell \nabla \cdot [\dots] = \nabla \cdot (\underline{\beta}_\ell [\dots]) - \nabla \underline{\beta}_\ell \cdot [\dots],$$

we obtain finally

$$\begin{aligned} \bar{D}_t(\underline{\beta}_\ell e k_\ell) + \nabla \cdot \left[ \underline{\beta}_\ell \left( \tau_\ell(P, \mathbf{v}) + \frac{1}{2} e \tau_\ell(v_i, v_i, \mathbf{v}) \right) \right] \\ = \nabla \underline{\beta}_\ell \cdot \left( \tau_\ell(P, \mathbf{v}) + \frac{1}{2} e \tau_\ell(v_i, v_i, \mathbf{v}) \right) - e \underline{\beta}_\ell \bar{\varepsilon}_\ell \\ + (\bar{D}_t \underline{\beta}_\ell) e k_\ell + e \underline{\beta}_\ell \pi_\ell. \end{aligned}$$

Adding this to the balance equation for  $\underline{s}_\ell$  in part (a), the term  $e \underline{\beta}_\ell \bar{\varepsilon}_\ell$  cancels and we obtain

$$\bar{D}_t \underbrace{(\underline{s}_\ell + \underline{\beta}_\ell e k_\ell)}_{\underline{s}_\ell^*} + \nabla \cdot (\underline{\beta}_\ell \mathbf{q}_\ell) = \nabla \underline{\beta}_\ell \cdot \mathbf{q}_\ell + (\bar{D}_t \underline{\beta}_\ell) e k_\ell + e \underline{\beta}_\ell \pi_\ell$$

as required.

Problem 2, The key observations here are that

$$\nabla \times \bar{u}_\ell(x) = \frac{1}{\ell} \int d^d r (\nabla G)_\ell(r) \times \delta u(r; x)$$

and

$$f_{\ell i}^S(x) = \frac{1}{\ell} \left\{ \int d^d r (\partial_j G)_\ell(r) \delta u_i(r; x) \delta u_j(r; x) - \int d^d r (\partial_j G)_\ell(r) \delta u_i(r; x) \int d^d r' G_\ell(r') \delta u_j(r'; x) \right\}$$

which can be expressed entirely in terms of velocity-increments.

Since the latter are scale-local (both UV and IR) so are  $\nabla \times \bar{u}_\ell$  and  $f_{\ell i}^S$  and, thus,  $\Lambda_\ell$ , when  $u$  is Hölder continuous with exponent  $0 < h < 1$ . Therefore,

$$\delta \bar{u}_\Delta(r) = O(r \Delta^{h-1})$$

and

$$\delta u'_\delta(r) = O(\delta^h)$$

can be used to derive bounds such as

$$\Lambda_\ell(u, u, \bar{u}_\Delta) = O(\ell^{2h-1} \Delta^{h-1})$$

which vanishes for  $\Delta/\ell \rightarrow \infty$  and

$$\Lambda_\ell(u, u, u'_\delta) = O(\ell^{2h-2} \delta^h)$$

which vanishes for  $\delta/\ell \rightarrow 0$ . The same bounds hold no matter which of the three  $u$ 's is replaced by  $\bar{u}_\Delta$  or  $u'_\delta$ . Thus, helicity cascade is scale-local when  $u$  is Hölder continuous with exponent  $0 < h < 1$ .

Problem 3. a) It is enough to observe that

$$\lim_{v \rightarrow 0} \tanh\left(\frac{Lx}{2vt}\right) = \theta(x) - \theta(-x) = \begin{cases} -1 & x < 0 \\ 0 & x = 0 \\ +1 & x > 0 \end{cases}$$

for fixed  $Lx/t$ . Thus,

$$\begin{aligned} \lim_{v \rightarrow 0} u^v(x,t) &= \frac{x}{t} - \frac{L}{t} [-\theta(-x) + \theta(x)] \\ &= \left(\frac{x+L}{t}\right) \theta(-x) + \left(\frac{x-L}{t}\right) \theta(x). \end{aligned}$$

b) We note first that

$$\begin{aligned} \partial_t u(x,t) &= \partial_t \left[ \left(\frac{x+L}{t}\right) \theta(-x) + \left(\frac{x-L}{t}\right) \theta(x) \right] \\ &= -\frac{1}{t} u(x,t) \end{aligned}$$

since  $d/dt(1/t) = -1/t^2$ . Next,

$$\frac{1}{2} u^2(x,t) = \frac{1}{2} \left(\frac{x+L}{t}\right)^2 \theta(-x) + \frac{1}{2} \left(\frac{x-L}{t}\right)^2 \theta(x)$$

in the sense of distributions (which allows us to ignore the inequality at  $x=0$ ). Thus, using  $\theta'(x) = \delta(x)$ ,

$$\begin{aligned} \partial_x \left( \frac{1}{2} u^2(x,t) \right) &= \frac{x+L}{t^2} \theta(-x) + \frac{x-L}{t^2} \theta(x) \\ &\quad + \frac{1}{2} \left[ -\left(\frac{x+L}{t}\right)^2 + \left(\frac{x-L}{t}\right)^2 \right] \delta(x) \\ &= \frac{1}{t} u(x,t) + \frac{1}{2} \left[ -\left(\frac{L}{t}\right)^2 + \left(\frac{L}{t}\right)^2 \right] \delta(x) \end{aligned}$$

Thus, finally,

$$\partial_t u(x,t) + \partial_x \left( \frac{1}{2} u^2(x,t) \right) = -\frac{1}{t} u(x,t) + \frac{1}{t} u(x,t) \\ = 0$$

in the sense of distributions.

c) A more formal calculation which gives the same result is as follows:

$$\int_0^\infty dt \int_{-L}^L dx \left[ u(x,t) \partial_t \varphi(x,t) + \frac{1}{2} u^2(x,t) \partial_x \varphi(x,t) \right] + \int_{-L}^L dx u_0(x) \varphi(x,0) \\ = \int_0^\infty dt \int_{-L}^L dx \left[ -\partial_t u(x,t) \cdot \varphi(x,t) + \frac{1}{2} u^2(x,t) \partial_x \varphi(x,t) \right]$$

by integration by parts in  $t$

$$= \int_0^\infty dt \left\{ \int_{-L}^0 dx \left[ \left( \frac{x+L}{t^2} \right) \varphi(x,t) + \frac{1}{2} \left( \frac{x+L}{t} \right)^2 \partial_x \varphi(x,t) \right] \right. \\ \left. + \int_0^L dx \left[ \left( \frac{x-L}{t^2} \right) \varphi(x,t) + \frac{1}{2} \left( \frac{x-L}{t} \right)^2 \partial_x \varphi(x,t) \right] \right\}$$

by substituting  $u(x,t)$ ,  $\partial_t u(x,t)$

$$= \int_0^\infty \frac{dt}{t^2} \left\{ \int_{-L}^0 dx \partial_x \left[ \frac{1}{2} (x+L)^2 \varphi(x,t) \right] + \int_0^L dx \partial_x \left[ \frac{1}{2} (x-L)^2 \varphi(x,t) \right] \right\}$$

$$= \int_0^\infty \frac{dt}{t^2} \left\{ \frac{L^2}{2} \varphi(0^-, t) - \frac{L^2}{2} \varphi(0^+, t) \right\} = 0!$$

Problem 4, a) Using

$$\frac{1}{2}u^2 = \frac{1}{2}\left(\frac{x+L}{t}\right)^2 \theta(-x) + \frac{1}{2}\left(\frac{x-L}{t}\right)^2 \theta(x)$$

$$\frac{1}{3}u^3 = \frac{1}{3}\left(\frac{x+L}{t}\right)^3 \theta(-x) + \frac{1}{3}\left(\frac{x-L}{t}\right)^3 \theta(x)$$

one gets

$$\partial_t \left( \frac{1}{2}u^2 \right) = - \left[ \frac{(x+L)^2}{t^3} \theta(-x) + \frac{(x-L)^2}{t^3} \theta(x) \right]$$

and

$$\begin{aligned} \partial_x \left( \frac{1}{3}u^3 \right) &= \left[ \frac{(x+L)^2}{t^3} \theta(-x) + \frac{(x-L)^2}{t^3} \theta(x) \right] \\ &+ \underbrace{\left[ -\frac{1}{3}\left(\frac{x+L}{t}\right)^3 + \frac{1}{3}\left(\frac{x-L}{t}\right)^3 \right]}_{= -\frac{2}{3}\left(\frac{L}{t}\right)^3} \delta(x) \\ &= -\frac{2}{3}\left(\frac{L}{t}\right)^3 \delta(x) = -\frac{1}{12}(\Delta u)^3 \delta(x). \end{aligned}$$

Unlike the case for the momentum balance, we see that the delta-functions do not cancel in the energy balance! We finally obtain that

$$\partial_t \left( \frac{1}{2}u^2 \right) + \partial_x \left( \frac{1}{3}u^3 \right) = -\frac{1}{12}(\Delta u)^3 \delta(x)$$

in the sense of distributions.

(b) Using  $\varepsilon^\nu(x, t) \approx \frac{L^4}{4\nu t^4} \operatorname{sech}^4\left(\frac{Lx}{2\nu t}\right)$ , one gets that

$$\int_{-L}^L \varphi(x) \varepsilon^\nu(x, t) dx = \frac{1}{2} \left(\frac{L}{t}\right)^3 \int_{-L^2/2\nu t}^{L^2/2\nu t} \varphi\left(\frac{2\nu t}{L} u\right) \operatorname{sech}^4 u du$$

with the change of variables  $u = Lx/2\nu t$ . Taking the limit  $\nu \rightarrow 0$

$$\begin{aligned} \lim_{\nu \rightarrow 0} \int_{-L}^L \varphi(x) \varepsilon^\nu(x, t) dx &= \frac{1}{2} \left(\frac{L}{t}\right)^3 \int_{-\infty}^{+\infty} \varphi(0) \cdot \operatorname{sech}^4 u du \\ &= \frac{2}{3} \left(\frac{L}{t}\right)^3 \varphi(0) \quad \text{using } \int_{-\infty}^{+\infty} \operatorname{sech}^4 u du = \frac{4}{3} \\ &= \frac{1}{12} (\Delta u)^3 \varphi(0). \end{aligned}$$

Problem 5. Using the analytic expression for the sawtooth solution, one easily calculates that

$$\begin{aligned} \delta u_s^\nu(r; t) &= u^\nu\left(\frac{r}{2}, t\right) - u^\nu\left(-\frac{r}{2}, t\right) \\ &= \frac{r}{t} - \frac{2L}{t} \tanh\left(\frac{Lr}{4\nu t}\right) \\ &= \frac{r}{t} - \frac{2L}{t} \tanh\left(\frac{\Delta u \cdot r}{8\nu}\right) \end{aligned}$$

with  $\Delta u = 2L/t$ .



Since

$$\tanh(x) = \text{sign}(x) + O(e^{-2|x|}), \quad |x| \gg 1,$$

$$\delta u_s^v(r, t) \approx \frac{r}{t} - \frac{2L}{t} \text{sign}(r) \quad \text{for } |r| \gg \frac{v}{\Delta u}$$

If, furthermore,  $|r| \ll L$ , then

$$\delta u_s^v(r, t) \approx -\frac{2L}{t} \text{sign}(r) = -(\Delta u) \cdot \text{sign}(r)$$

for  $v/\Delta u \ll |r| \ll L$ .

On the other hand,

$$\tanh(x) = x + O(x^3), \quad |x| \ll 1.$$

Therefore,

$$\delta u_s^v(r, t) \approx \frac{r}{t} - \frac{2L}{t} \cdot \frac{Lr}{4vt}$$

$$= \frac{r}{t} \left( 1 - \frac{L^2}{2vt} \right)$$

for  $|r| \ll v/\Delta u$ .