

Homework #6

Problem 1. (a) By definition

$$\begin{aligned}
 T(u_i, u_j, u_k) &= \overline{u_i u_j u_k} - \overline{u_i} T(u_j, u_k) - \overline{u_j} T(u_i, u_k) - \overline{u_k} T(u_i, u_j) \\
 &\quad - \overline{u_i} \overline{u_j} \overline{u_k} \\
 &= \overline{u_i u_j u_k} - \overline{u_i} [\overline{u_j u_k} - \overline{u_j} \overline{u_k}] - \overline{u_j} [\overline{u_i u_k} - \overline{u_i} \overline{u_k}] \\
 &\quad - \overline{u_k} [\overline{u_i u_j} - \overline{u_i} \overline{u_j}] - \overline{u_i} \overline{u_j} \overline{u_k} \\
 &= \overline{u_i u_j u_k} - \overline{u_i} \overline{u_j u_k} - \overline{u_j} \overline{u_i u_k} - \overline{u_k} \overline{u_i j} + 2\overline{u_i} \overline{u_j} \overline{u_k}.
 \end{aligned}$$

(b) Recall that $W_\ell(\alpha) = \ln Z_\ell(\alpha)$ with

$$Z_\ell(\alpha) = \overline{(\exp(\alpha \cdot u))}_\ell.$$

Thus,

$$\overline{u_i}(\alpha) = \frac{\partial}{\partial \alpha_i} W(\alpha) = \frac{1}{Z(\alpha)} \frac{\partial Z(\alpha)}{\partial \alpha_i} = \frac{1}{Z(\alpha)} \overline{(u_i e^{\alpha \cdot u})}_\ell$$

Similarly,

$$\begin{aligned}
 T_{ij}(\alpha) &= \frac{\partial^2}{\partial \alpha_i \partial \alpha_j} W(\alpha) \\
 &= \frac{\partial}{\partial \alpha_j} \left[\frac{1}{Z(\alpha)} \overline{(u_i e^{\alpha \cdot u})}_\ell \right] \\
 &= \frac{1}{Z(\alpha)} \overline{(u_i u_j e^{\alpha \cdot u})}_\ell - \frac{1}{Z^2(\alpha)} \overline{(u_i e^{\alpha \cdot u})}_\ell \overline{(u_j e^{\alpha \cdot u})}_\ell
 \end{aligned}$$

and

$$\begin{aligned}
 \pi_{ijk}(\alpha) &= \frac{\partial^3}{\partial \alpha_i \partial \alpha_j \partial \alpha_k} W(\alpha) \\
 &= \frac{\partial}{\partial \alpha_k} \left[\frac{1}{Z(\alpha)} \overline{(u_i u_j e^{\alpha \cdot u})}_L - \frac{1}{Z^2(\alpha)} \overline{(u_i e^{\alpha \cdot u})}_L \overline{(u_j e^{\alpha \cdot u})}_L \right] \\
 &= \frac{1}{Z(\alpha)} \overline{(u_i u_j u_k e^{\alpha \cdot u})}_L - \frac{1}{Z^2(\alpha)} \overline{(u_k e^{\alpha \cdot u})}_L \overline{(u_i u_j e^{\alpha \cdot u})}_L \\
 &\quad - \frac{1}{Z^2(\alpha)} \overline{(u_i u_k e^{\alpha \cdot u})}_L \overline{(u_j e^{\alpha \cdot u})}_L - \frac{1}{Z^2(\alpha)} \overline{(u_i e^{\alpha \cdot u})}_L \overline{(u_j u_k e^{\alpha \cdot u})}_L \\
 &\quad + \frac{2}{Z^3(\alpha)} \overline{(u_i e^{\alpha \cdot u})}_L \overline{(u_j e^{\alpha \cdot u})}_L \overline{(u_k e^{\alpha \cdot u})}_L.
 \end{aligned}$$

Finally, setting $\alpha = 0$, we get again that (since $Z(0) = 1$)

$$\begin{aligned}
 \pi(u_i, u_j, u_k) &= \pi_{ijk}(0) \Big|_{\alpha=0} \\
 &= \overline{u_i u_j u_k} - \overline{u_k} \overline{u_i u_j} - \overline{u_i u_k} \overline{u_j} - \overline{u_j u_k} \overline{u_i} + 2\overline{u_i} \overline{u_j} \overline{u_k}.
 \end{aligned}$$

(c) In Homework #4, Problem 2(b) it was shown that 3rd-order cumulants are always shift-invariant. Since

$$\tau_L(u_i, u_j, u_k) = \langle (\delta u_i)(\delta u_j)(\delta u_k) \rangle_L^c$$

Employing the shift $\delta u_i(r; x) \rightarrow \delta u_i(r; x) - u_i(x) = \delta u_i(r; x)$,

$$\begin{aligned}
 \tau_L(u_i, u_j, u_k) &= \langle (\delta u_i)(\delta u_j)(\delta u_k) \rangle_L^c \\
 &= \langle \delta u_i \delta u_j \delta u_k \rangle_L - \langle \delta u_i \rangle_L \langle \delta u_j \delta u_k \rangle_L - \langle \delta u_j \rangle_L \langle \delta u_i \delta u_k \rangle_L \\
 &\quad - \langle \delta u_k \rangle_L \langle \delta u_i \delta u_j \rangle_L + 2 \langle \delta u_i \rangle_L \langle \delta u_j \rangle_L \langle \delta u_k \rangle_L.
 \end{aligned}$$

Problem 2. (a) Using the relation

$$\int_0^\infty dk E_{f_*}(k) = \langle |f_*|^2 \rangle$$

we see that $\langle |f_*|^2 \rangle < +\infty$ if $E_{f_*}(k) \sim k^{-n}$ for $n > 1$, but that $\langle |f_*|^2 \rangle = +\infty$ if $E_{f_*}(k) \sim k^{-n}$ for $n \leq 1$. Thus, f is inertial-range if $n > 1$ and dissipation-range if $n \leq 1$.

(b) Since

$$\langle |u_*|^2 \rangle < +\infty$$

(certainly in decaying turbulence), u_v is inertial-range. However,

$$\langle |\nabla u|_v^2 \rangle = \frac{\varepsilon}{\nu} \rightarrow \infty$$

as $v \rightarrow 0$, so that $(\nabla u)_v$ is dissipation-range. Since the pressure has

$$\|\delta p_*(r)\|_q \leq (\text{const.}) \|\delta u_*^{(v)}\|_{2q}^2 = O(r^{\frac{5}{2q}/q})$$

it follows that p_* is even more regular than u_* . Thus, pressure p_v is inertial-range. However, the evidence is that $\zeta_{2q}^{(u)} \leq \frac{2}{3}q$, $q \geq 3/2$ (to account for energy dissipation) so that

$$\sigma_q^{(p)} = \frac{\zeta_q^{(p)}}{q} \approx \sigma_{2q}^{(u)} \leq \frac{2}{3}$$

for $q \geq 3/2$. Thus, the pressure-gradient ∇p_v has

$$\sigma_q^{(\nabla p)} = \sigma_q^{(p)} - 1 \leq -\frac{1}{3} < 0$$

\Rightarrow pressure-gradient is dissipation-range.

(c) All of those are inertial-range. In fact,

$$\bar{f}_{v,l}(x) = \int d^d r G_\ell(r) f_v(x+r)$$

$$\xrightarrow{v \rightarrow 0} \int d^d r G_\ell(r) \bar{f}_*(x+r) = \bar{f}_{*,l}(x)$$

which is a smoother function of x , even if f_* is only a distribution.

(d) Since

$$f'_{v,l} = f_v - \bar{f}_{v,l}$$

$$\xrightarrow{v \rightarrow 0} f_* - \bar{f}_{*,l},$$

$f'_{v,l}$ converges as $v \rightarrow 0$ to an ordinary function $f'_{*,l}$ if and only if f_v does so. Thus, the answers in (d) are the same as those for (b)

$$u'_\ell \quad \text{inertial-range}$$

$$\nabla u'_\ell \quad \text{dissipation-range}$$

$$p'_\ell \quad \text{inertial-range}$$

$$\nabla p'_\ell \quad \text{dissipation-range}$$

Problem 3. (a) After integrating over space domain Ω , the term $\nabla \cdot J_l^{(k)}$ vanishes because of the condition that no energy flows across the boundary $\partial\Omega$. Thus,

$$\frac{d}{dt} \int dx k_l = \int dx [\Pi_l - \varepsilon_l' + Q_l'].$$

Integrating in time over the interval $t \in [0, T]$ then gives

$$\begin{aligned} & \int dx k_l(T) - \int dx k_l(0) \\ &= \int_0^T dt \int dx [\Pi_l - \varepsilon_l' + Q_l']. \end{aligned}$$

On the other hand, $\varepsilon_l' = \sqrt{(\nabla v)^2} - \sqrt{(\nabla \bar{v})^2}$, so that

$$\int dx \varepsilon_l' = \sqrt{\int dx |\nabla v|^2} - \sqrt{\int dx |\nabla \bar{v}|^2}$$

since $\int dx \bar{f}_l = \int dx f$ for any function f . Substituting into the previous equality and rearranging terms gives

$$\begin{aligned} \sqrt{\int_0^T dt \int dx |\nabla v|^2} &= \int_0^T dt \int dx [\Pi_l + \sqrt{|\nabla \bar{v}_l|^2} + Q_l'] \\ &\quad - \left. \int dx k_l(t) \right|_{t=0}^{t=T}. \end{aligned}$$

(b) Because of convexity of the function $|v|^2$ in v , it follows that $|\nabla_e|^2 \leq \overline{(|v|^2)_e}$, so that

$$\frac{1}{2} \int d^d x |\nabla_e|^2 \leq \frac{1}{2} \int d^d x \overline{(|v|^2)_e} = \frac{1}{2} \int d^d x |v|^2.$$

Since $k_e = \frac{1}{2} \overline{(|v|^2)_e} - \frac{1}{2} |\nabla_e|^2$, the last inequality is equivalent to

$$\int d^d x k_e (+) \geq 0$$

for all $t \in [0, T]$. Applying this inequality to $t = T$ gives

$$v \int_0^T dt \int d^d x |\nabla v|^2 \leq \int_0^T dt \int d^d x [\Pi_e + v |\nabla \tilde{v}_e|^2 + Q_e^{-1}] + \int d^d x k_e(0).$$

(c) We now apply the inequalities derived in class and the course notes, such as

$$\begin{aligned} \left| \frac{1}{12} \int d^d x \Pi_e \right| &\leq \|\Pi_e\|_1 \\ &\leq \|\Pi_e\|_{p/3} \quad \text{for } p \geq 3 \\ &\leq (\text{const.}) \frac{V(\epsilon)}{L} \left(\frac{\ell}{L} \right)^{3S-1} \end{aligned}$$

$$\begin{aligned}
\frac{\nu}{|S^2|} \int d^3x |\nabla \tilde{v}_\ell|^2 &= \nu \|\nabla \tilde{v}_\ell\|_2^2 \\
&\leq \nu \|\nabla v\|_p^2 \quad \text{for } p \geq 3 > 2 \\
&\leq (\text{const.}) \frac{\nu V^2(+)}{\ell^2} \left(\frac{\ell}{L}\right)^{2s} \\
&= (\text{const.}) \frac{\nu V^2(+)}{L^2} \left(\frac{\ell}{L}\right)^{2s-2}
\end{aligned}$$

Since $Q'_\ell = T_\ell(f; v) = \int d^3r G_\ell(r) \delta f(r) \cdot \delta v(r) - \int d^3r G_\ell(r) \delta f(r) \cdot \int d^3r' G_\ell(r') \delta v(r)$

we may apply the same approach as for $T_\ell = T_\ell(v, v)$ to show

$$\begin{aligned}
\left| \frac{1}{|S^2|} \int d^3x Q'_\ell \right| &\leq \|Q'_\ell\|_1 \\
&\leq \|Q'_\ell\|_{p/2} \quad \text{for } p/2 \geq 3/2 > 1 \\
&\leq \int d^3r G_\ell(r) \|\delta f(r)\|_p \|\delta v(r)\|_p \\
&\quad + \int d^3r G_\ell(r) \|\delta f(r)\|_p \int d^3r' G_\ell(r') \|\delta v(r')\|_p \\
&\leq (\text{const.}) \frac{V^3(+)}{L^3} \left(\frac{\ell}{L}\right)^{2s}
\end{aligned}$$

if one assumes (in a dimensionally correct form) that

$$\|\delta F(\cdot, \cdot; r)\|_p \leq \frac{V^2(+)^s}{L} \left| \frac{r}{L} \right|^s, \quad |r| < L.$$

Of course, by the results in class,

$$\frac{1}{\beta^2} \int dx k_\ell(x) = V^2(0) \left(\frac{\ell}{L} \right)^{2s}.$$

Putting all of the various estimates together gives

$$\langle \varepsilon \rangle \leq (\text{const.}) \frac{V^3}{L} \left[\left(\frac{\ell}{L} \right)^{3s-1} + \frac{1}{Re} \left(\frac{\ell}{L} \right)^{2s-2} + \left(\frac{\ell}{L} \right)^{2s} \right] \\ + (\text{const.}) \frac{V^2}{T} \left(\frac{\ell}{L} \right)^{2s}$$

with $V = \max_{t \in [0, T]} V(t)$ and $Re := VL/V$. Since $s < 1$

$$\left(\frac{\ell}{L} \right)^{2s} = \left(\frac{\ell}{L} \right)^{3s-1} \left(\frac{\ell}{L} \right)^{1-s} < \left(\frac{\ell}{L} \right)^{3s-1}$$

for $\ell < L$ and

$$\frac{V^3}{L} \left(\frac{\ell}{L} \right)^{3s-1} + \frac{V^2}{T} \left(\frac{\ell}{L} \right)^{2s} = \frac{V^3}{L} \left(\frac{\ell}{L} \right)^{3s-1} \left[1 + \frac{L}{VT} \left(\frac{\ell}{L} \right)^{1-s} \right] \\ \leq \left(1 + \frac{L}{VT} \right) \times \frac{V^3}{L} \left(\frac{\ell}{L} \right)^{3s-1} \quad \ell < L.$$

Thus, we may absorb the last two terms into the first one and obtain

$$\langle \varepsilon \rangle \leq (\text{const.}) \frac{V^3}{L} \left[\left(\frac{\ell}{L} \right)^{3s-1} + \frac{1}{Re} \left(\frac{\ell}{L} \right)^{2s-2} \right].$$

(d) It is a simple calculus exercise to minimize the above upper bound by differentiating with respect to ℓ , and this yields the minimum (smallest bound) for

$$\ell = C_s L Re^{-1/(1+s)}$$

with $C_s = \left(\frac{2-2s}{3s-1} \right)^{\frac{1}{s+1}}$. Note that for this choice the two terms in the previous upper bound became of the same order of magnitude and, thus,

$$\langle \varepsilon \rangle \leq (\text{const.}) \frac{V^3}{L} Re^{-(3s-1)/(s+1)}.$$

Clearly, if $s > \frac{1}{3}$, then $\langle \varepsilon \rangle \rightarrow 0$ as $Re \rightarrow \infty$, and the rate of viscous energy dissipation must vanish as an inverse power of Re .

(e) If, instead,

$$\langle \varepsilon \rangle \sim (\text{const.}) \frac{V^3}{L} Re^{-\alpha} \quad \text{as } Re \rightarrow \infty$$

then one arrives at a contradiction unless

$$\frac{3s-1}{s-1} \leq \alpha$$

$$\Leftrightarrow s \leq \frac{\alpha+1}{3-\alpha} := s_\alpha.$$

In terms of inertial-range structure-function scaling exponents, this translates into the condition

$$s_p \leq s_{\alpha p} \quad \text{for } p \geq 3.$$

In a laminar flow, $\langle \varepsilon \rangle = \frac{(\text{const.})}{Re}$ but if $\langle \varepsilon \rangle$ vanishes just a bit slower than this, the previous argument shows that the Navier-Stokes velocity cannot have smoothness $s > s_\alpha \doteq 1 + (\alpha - 1) = \alpha$ for $1 - \alpha \ll 1$, holding uniformly in viscosity. On the other hand, if $\alpha \ll 1$ and the energy dissipation rate is nearly independent of Re , then the critical smoothness exponent $s_\alpha \doteq \frac{1}{3} + \frac{4\alpha}{9}$, which is just slightly larger than Onsager's exponent $1/3$. The conclusions of the argument are thus very robust and do not depend upon exact independence of viscosity.

Problem 4. (a) The result

$$\tilde{\tau}_l(u, u) = \overline{(\tau_\delta(u, u))_l} + \tau_l(\bar{u}_\delta, \bar{u}_\delta)$$

is just the Germano identity.

(b) In general, $\tau_l(u, u)$ denotes the stress obtained from velocity modes in u at scales $< l$. Thus, $\tau_l(\bar{u}_\delta, \bar{u}_\delta)$ denotes the stress obtained from velocity modes in \bar{u}_δ at scales $< l$. However, \bar{u}_δ contains only scales $> \delta$. Thus, $\tau_l(\bar{u}_\delta, \bar{u}_\delta)$ can be interpreted as the stress at scale l from the velocity modes in the range between δ and l . Note that $\tau_l(\bar{u}_\delta, \bar{u}_\delta)$ is a positive matrix, as a stress should be. Next, note that $\tau_\delta(u, u)$ is the stress at length-scale δ from the modes at scales $< \delta$. Thus, the filtered quantity $\overline{(\tau_\delta(u, u))_l}$ is the stress at scales l from the velocity modes at scales $< \delta$. Again, $\overline{(\tau_\delta(u, u))_l}$ is a positive matrix, as it should be.

(c) If u is Hölder continuous with exponent h , then

$$\tau_\delta(u, u) = O(\delta^{2h}),$$

as shown in class. Since additional filtering will not change this, i.e.

$$|\tilde{f}_l| \leq \int dr G_l(r) |f(x+r)| \leq \|f\|_\infty,$$

it follows at once that also

$$\overline{(\tau_\delta(u, u))_l} = O(\delta^{2h}).$$

Problem 5. (c) By general results for $T_\ell(f, g)$

$$f_\ell^v = \int d^d r G_\ell(r) \delta u(r) \times \delta w(r) - \int d^d r G_\ell(r) \delta u(r) \times \int d^d r' G_\ell(r') \delta w(r').$$

(b) If G has compact support, then

$$\begin{aligned} |f_\ell^v| &\leq \int d^d r G_\ell(r) |\delta u(r)| \cdot |\delta w(r)| \\ &\quad + \int d^d r G_\ell(r) |\delta u(r)| \cdot \int d^d r' G_\ell(r') |\delta w(r')| \\ &\leq 2 \delta u(l) \delta w(l) \end{aligned}$$

with $\delta u(l) = \sup_{r \leq l} |\delta u(r)|$, $\delta w(l) = \sup_{r \leq l} |\delta w(r)|$. However, w is not Hölder continuous in the limit $V \rightarrow 0$, so we might as well take

$$\begin{aligned} |\delta w(r)| &= |w(x+r) - w(x)| \\ &\leq |w(x+r)| + |w(x)| \leq 2 \|w\|_\infty. \end{aligned}$$

Thus,

$$|f_\ell^v| \leq 4 \|w\|_\infty \delta u(l).$$

(c) The bound is probably not optimal, since u is inertial-range but w is dissipation-range. Thus, cancellations should occur in the integral over r .

The correlation coefficient can be estimated by a ratio of time-scales:

$$\rho(\delta w(l), \delta u(l)) \approx \frac{\delta u(l)/l}{w_{\max}} \ll 1$$

Thus, a better estimate should be — heuristically —

$$|f_e^v| = O^*(\delta u(l) w_{\max} \cdot \frac{\delta u(l)/l}{w_{\max}})$$

$$= O^*\left(\frac{\delta u^2(l)}{l}\right).$$

Note that this is the same estimate which was obtained (rigorously!) for the subgrid force f_e^s . In fact, using

$$f_e^v = f_e^s + \nabla k_e \quad , \quad k_e = \frac{1}{2} \operatorname{tr} T_e(u, u)$$

one can indeed show rigorously that

$$|f_e^v| = O\left(\frac{\delta u^2(l)}{l}\right).$$

Here, we have used also the result

$$\begin{aligned} \partial_i k_e &= \frac{1}{2l} \left\{ \int d^d r (\partial_i G)_e(r) |\delta u(r)|^2 \right. \\ &\quad \left. - 2 \int d^d r (\partial_i G)_e(r) \delta u(r) \cdot \int d^d r' G_e(r') \delta u(r') \right\} \\ &= O\left(\frac{\delta u^2(l)}{l}\right). \end{aligned}$$

Thus, the heuristic argument about cancellations leads in this case to a result which can be rigorously verified!

(d) Let us first examine the issue of scale locality using the formula

$$f_\ell^v = \int d^d r G_\ell(r) \delta u(r) \times \delta w(r) - \int d^d r G_\ell(r) \delta u(r) \times \int d^d r' G_\ell(r') \delta w(r')$$

We already know that $\delta u(r)$ is both IR and UV local when u is Hölder continuous with an exponent $0 < h < 1$. What about $\delta w(r)$? It is certainly IR-local, since

$$\delta \bar{w}_\Delta(r) = r \cdot \nabla \bar{w}_\Delta(x) = O(r \Delta^{h-1})$$

and this goes to zero for $\Delta/r \gg 1$, when $h < 1$. However, the vorticity increment is not UV-local, since

$$|\delta w'_\delta(r)| = |\omega'_\delta(x+r) - \omega'_\delta(x)| \cong 2\omega_{\max}$$

does not need to vanish at all for $\delta \ll r$. Thus, we can draw no conclusion about UV locality of f_ℓ^v . Although $\delta w(r)$ is not UV local, there may be sufficient cancellations in the integral over r to ensure UV-locality.

In fact, this can be proved using

$$f_\ell^v(u, u) = f_\ell^s(u, u) + \nabla k_\ell(u, u),$$

from which estimates such as

$$f_\ell^v(u, u'_\delta) = O\left(\frac{\delta u(\ell)}{\ell} \delta u(\delta)\right) = O(\ell^{h-1} \delta^h)$$

can be derived and this goes to zero as $\delta \rightarrow 0$, if $h > 0$.