Fusion and Inference from Multiple and Massive Disparate Data Sources

\[ f: \mathbb{E} \rightarrow M = \{(V_i, x_i, t_i)\} \]

\[ g: M \rightarrow \{G_t(M)\} \]

\( f \) extracts “events” \((V_i, x_i, t_i)\) -- who does what when

\( g \) produces time series of attributed graphs \( \{G_t(M)\} \)

Anomaly Detection in Time Series of Attributed Graphs